				••••				_
		USPAT; US-PGP UB; EPO; JPO; 2004/06/24 DERWEN 16:37 T; IBM_ID		(target\$2 or mark\$2)near5(surface or substrate or paper near3 sheet or board or layer)same (camera\$1 or sensor\$2 or captur\$4 near3 device\$1 or imag\$3 near3 pickup)	10498	L20	BRS	ω
		2004/06/24	USPAT; US-PGP UB; EPO; JPO; DERWEN T; IBM_TD B	18 and frame\$1	Н	L19	BRS	N
		2004/06/24 114:27	USPAT; US-PGP UB; EPO; JPO; DERWEN T; IBM_TD B	6681151.pn.	N	L18	BRS	L }
Error Defini	Comments	Time Stamp	DBs	Search Text	Hits	T #	Туре	• •

	Туре	#	Hits	Search Text	DBs	Time Stamp	Comments	Error
44	BRS	L21	1	20 same detec\$5 near5 (target\$2 or mark\$2)same (frame-by-frame or frame near3 frame)near5 analysis	USPAT; US-PGP UB; EPO; JPO; DERWEN T; IBM_TD B	USPAT; US-PGP UB; EPO; 2004/06/24 JPO; DERWEN 14:39 T; IBM_TD B		
UI	BRS	L23	14	22 and (user or "user's") near5 mark\$4	USPAT; US-PGP UB; EPO; JPO; DERWEN T; IBM_TD B	2004/06/24 14:45		
0	BRS	L22	21	20 and detec\$5 near5 (target\$2 or mark\$2)same (frame-by-frame or frame near3 frame)	USPAT; US-PGP UB; EPO; JPO; DERWEN T; IBM_TD B	2004/06/24		

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Ш	hr	H	
BRS	BRS	BRS	Туре
L26	L25	L24	L#
Ц	N	Ν	Hits
25 and (frame-by-frame or frame near3 frame)	24 and(target\$2 or mark\$2) same(detec\$4 or track\$3)	5657251.pn.	Search Text
USPAT; US-PGP UB; EPO; JPO; DERWEN T; IBM_TD B	USPAT; US-PGP UB; EPO; JPO; DERWEN T; IBM_TD B	USPAT; US-PGP UB; EPO; JPO; DERWEN T; IBM_TD B	DBs
2004/06/24 15:06	2004/06/24 15:06	2004/06/24 15:04	Time Stamp
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	11 BRS	10 BRS	Туре
	L28	L27	L #
11	2201	7	Hits
(detect\$6 or inspect\$6) near7(target\$2 or mark\$2)same blank near3(surface or substrate or paper near3 sheet or board or layer)same (camera\$1 or sensor\$2 or	(detect\$6 or inspect\$6) near7(target\$2 or mark\$2)near5(surface or substrate or paper near3 sheet or board or layer)same (camera\$1 or sensor\$2 or captur\$4 near3 device\$1 or imag\$3 near3 pickup or CCD or "CCD")	19 and (recogn\$4 or locat\$3)near5(target\$2 or mark\$1)	Search Text
USPAT; US-PGP UB; EPO; JPO; DERWEN T;	USPAT; US-PGP UB; EPO; 2004, JPO; 16:39 DERWEN 16:39 T; IBM_TD B	USPAT; US-PGP UB; EPO; 2004, JPO; DERWEN 15:5: T; IBM_TD B	DBs
2004/06/24 16:40	2004/06/24 16:39	2004/06/24 15:57	Time Stamp
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	Туре	L #	Hits	Search Text	DBs	Time Stamp	Comments	Error Definition	Err
1	BRS	Ľ3	1558	detect\$3 near5(mark\$2 or symbol\$2 or target)near5(surface or substrate or paper near3 sheet or board or layer)same (camera\$1 or sensor\$2)	USPAT; US-PGP UB; EPO; JPO; DERWEN T; IBM_TD B	2004/06/19 11:15			0
N	BRS	Ľ4	2 1	3 and (user or "user's" or operator)near5(mark\$3 or draw\$3 or writ\$4)with(surface or substrate or paper near3 sheet or layer or board)	USPAT; US-PGP UB; EPO; JPO; DERWEN T; IBM_TD B	2004/06/19 11:23			0
ω	BRS	Ľ 5	O	4 and ineractive near3 game\$1	USPAT; US-PGP UB; EPO; JPO; DERWEN T; IBM_TD B	2004/06/19 11:23			0

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BRS	BRS	BRS	Туре
Ľ3	L2	L1	L #
} ⊷4	36	ω	Hits
((draw\$3 or writ\$3) near3(target or mark))same detect\$3 near5(movement or displacement)near5(surface or substrate or paper near3 sheet or board or layer)same (camera\$1 or sensor\$2)	((draw\$3 or writ\$3)near3(target or mark))near5(surface or substrate or paper near3 sheet or board or layer)same (camera\$1 or sensor\$2)	(draw\$3 near3(target or mark))near10(surface or substrate or paper near3 sheet or board or layer)same robot\$3	Search Text
USPAT; US-PGP UB; EPO; JPO; DERWEN T; IBM_TD B	USPAT; US-PGP UB; EPO; JPO; DERWEN T; IBM_TD B	USPAT; US-PGP UB; EPO; JPO; DERWEN T; IBM_TD B	DBs
2004/06/18 16:28	2004/06/18 16:23	2004/06/18 16:05	Time Stamp
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BRS	BRS	BRS	Type
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N	N 8	<u>ი</u>	Hits
(draw\$3 or writ\$3)near5(mark or symbol or target)near7 (surface or substrate or paper near3 sheet or board or lyer) same detect\$3 near5(movement or displacement)near5(surface or substrate or paper near3 sheet or board or layer)same (camera\$1 or sensor\$2)	4 and (devic\$2 or implement or pen)near5(writ\$3 or draw\$3)	(draw\$3 or writ\$3)same US-PA detect\$3 near5(movement or UB; displacement)near5(surface EPO; or substrate or paper near3 JPO; sheet or board or DERW layer)same (camera\$1 or T; sensor\$2)	Search Text
USPAT; US-PGP UB; EPO; JPO; DERWEN T; IBM_TD B	USPAT; US-PGP UB; EPO; JPO; DERWEN T; IBM_TD B	TU GF	DBs
2004/06/18	2004/06/18 16:37	2004/06/18 17:08	Time Stamp
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	BRS	BRS	Туре
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) near5 ce or near3 ayer) ar3 oe or ngman)	(draw\$3 or writ\$3)near5(mark or symbol or target)near7 (surface or substrate or paper near3 sheet or board or layer) and detect\$3 near5(movement or displacement)near5(surface or substrate or paper near3 sheet or board or layer)same (camera\$1 or sensor\$2)	Search Text
	USPAT; US-PGP UB; EPO; JPO; DERWEN 17:42 T; IBM_TD B	USPAT; US-PGP UB; EPO; JPO; DERWEN T; IBM_TD B	DBs
	2004/06/18 17:42	2004/06/18 17:39	Time Stamp
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			Error Definition
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	Туре	L #	Hits	Search Text	DBs	Time Stamp	Comments	Error Definition
Н	BRS	L1	N	5521829.pn.	USPAT; US-PGP UB; EPO; JPO; DERWEN 09:47 T; IBM_TD B	2004/06/14 09:47		
N	BRS	Ľ2	4929	382/103,106,151,152,153,186 ,313,314,315,188,189,187;34 8/169,113,116,170,171,175;3 56/3;235/411.ccls.	USPAT; US-PGP UB; EPO; JPO; DERWEN I; IBM_TD	2004/06/14 10:29		
ω	BRS	L 3	7	2 and (video adj1 camera or camera)near3 robot adj1 arm	USPAT; US-PGP UB; EPO; JPO; DERWEN T; IBM_TD	2004/06/14 10:31		

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44	BRS	L4	103950	3 and track\$3 or trac\$3	USPAT; US-PGP UB; EPO; JPO; DERWEN T; IBM_TD B	2004/06/14			0
, б	BRS	Ľ5	N	3 and (track\$3 or trac\$3)	d E H	2004/06/14 11:26			0
<u> </u>	BRS	P. 6	N	6044165.pn.	USPAT; US-PGP UB; EPO; JPO; DERWEN T; IBM_TD B	2004/06/14 11:26			0

1-3	Type	#	Hits	Search Text	DBs	Time Stamp	Comments	Error Definition
7	BRS	L7	7	detec\$3 near3 (substrate or piece adj1 paper or writ\$3 adj1 implement or writ\$3 adj1 surface) same (sensor\$2 or camera\$2) same(robot adj1 arm)	USPAT; US-PGP UB; EPO; JPO; DERWEN T; IBM_TD B	2004/06/14 12:23		
8	BRS	L8	0	detec\$3 same (draw\$3 or writ\$3)near3 (substrate or piece adj1 paper or writ\$3 adj1 implement or writ\$3 adj1 surface) same (sensor\$2 or camera\$2) same(robot adj1 arm)	USPAT; US-PGP UB; EPO; JPO; DERWEN T; IBM_TD B	2004/06/14 12:25		
σ	BRS	L9	Ν	detec\$3 same (draw\$3 or writ\$3)near3 (substrate or piece adj1 paper or writ\$3 adj1 implement or writ\$3 adj1 surface) same (sensor\$2 or camera\$2) and(robot adj1 arm)	USPAT; US-PGP UB; EPO; JPO; DERWEN T; IBM_TD B	2004/06/14 12:25		

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